

Tuning Hierarchical Learned Indexes on Disk and Beyond

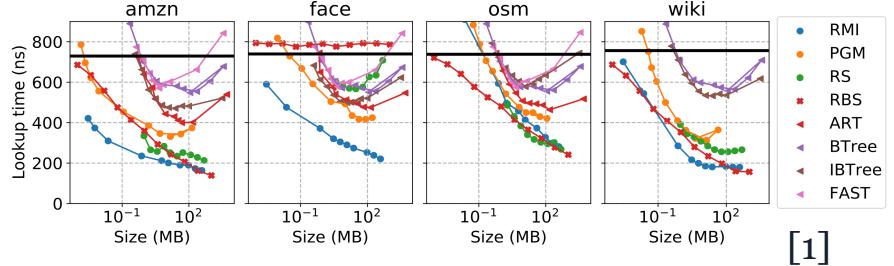


Supawit Chockchowwat

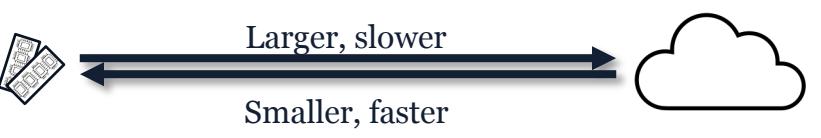
Department of Computer Science, College of Engineering, University of Illinois at Urbana-Champaign

Motivation

Learned indexes outperform in internal memory setting



Large data systems require external storages



Round-trip time violates fast-random-access assumption



Are fast random accesses necessary?

**How to design or tune
a learned index on external storage?**

Challenges

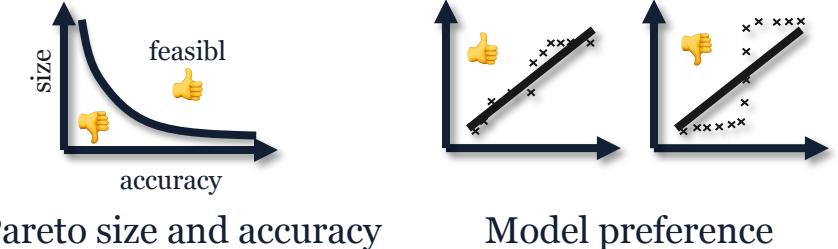
Storages have their unique performance profiles.



Index structures gain more design choices.

e.g., model, loss function, error distribution

Objective and constraints are more complex.



Objective: Cost under Ext. Mem. Model

Cost to access external memory dominates the total cost.



Represent the time to read x bytes from storage as $T(x)$

$$\text{e.g., affine storage profile: } T(x) = \frac{x}{\text{bandwidth}} + \text{latency}$$

Index search cost under EMM

$$T(s_L) + T(\Delta_L) + T(\Delta_{L-1}) + \dots + T(\Delta_1)$$

retrieve root layer
retrieve layer L-1
retrieve layer L-2
...
retrieve data layer

s_i : i-th layer size, Δ_i : precision at i-th layer

Experiments

Baselines: PostgreSQL [2], RocksDB [3], RMI [4]

Benchmark: Search On Sorted Data (SOSD) [1, 5]

1. **books:** Amazon sale popularity data
2. **fb:** Facebook user IDs, upsampled
3. **osm:** OpenStreetMap locations in Google S2 Cellids
4. **wiki:** Wikipedia article edit timestamps

Environment: Azure VM D4s_v3 (4 vCPUs, 16 GiB RAM), data and indexes on Azure NFS

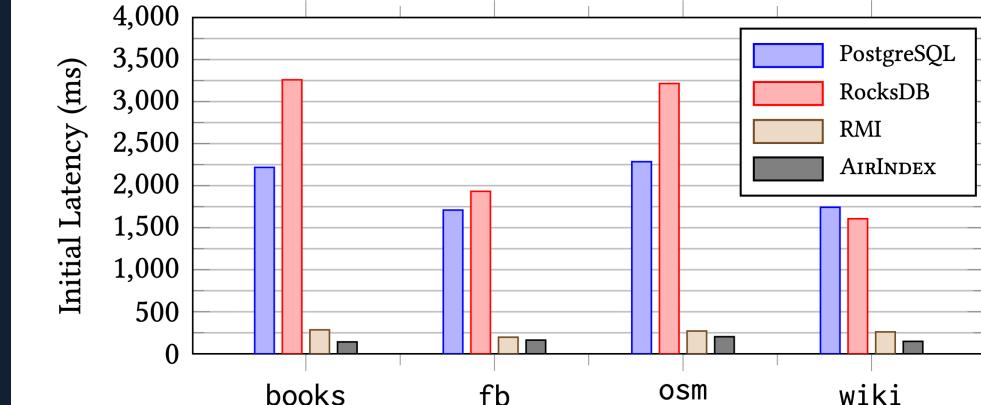


Figure 1: Initial lookup latency across SOSD datasets of different systems whose external memory is on Azure NFS.

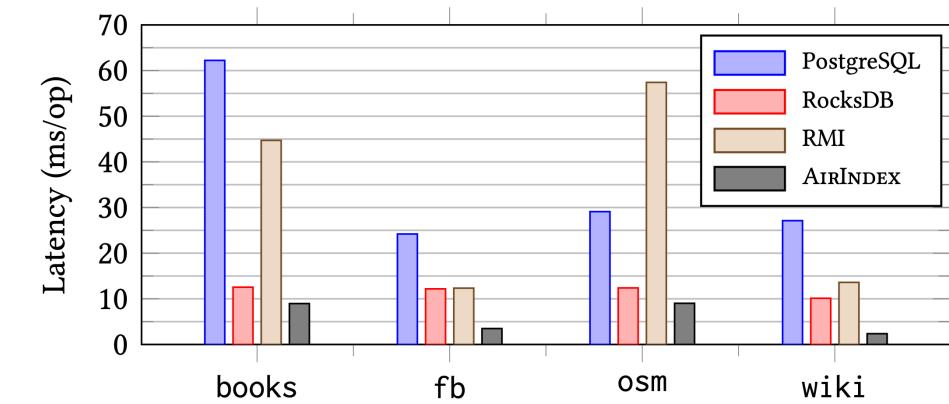


Figure 2: Average Lookup latency (over 70k queries) across SOSD datasets of different systems on Azure NFS.

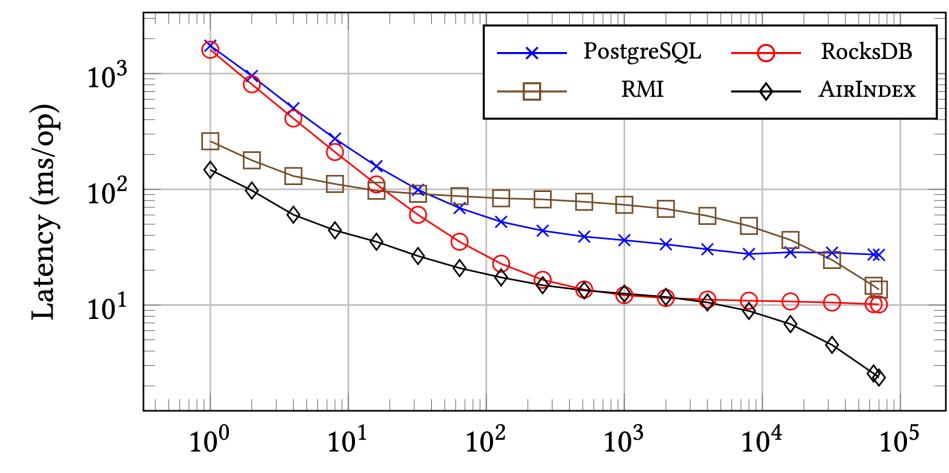
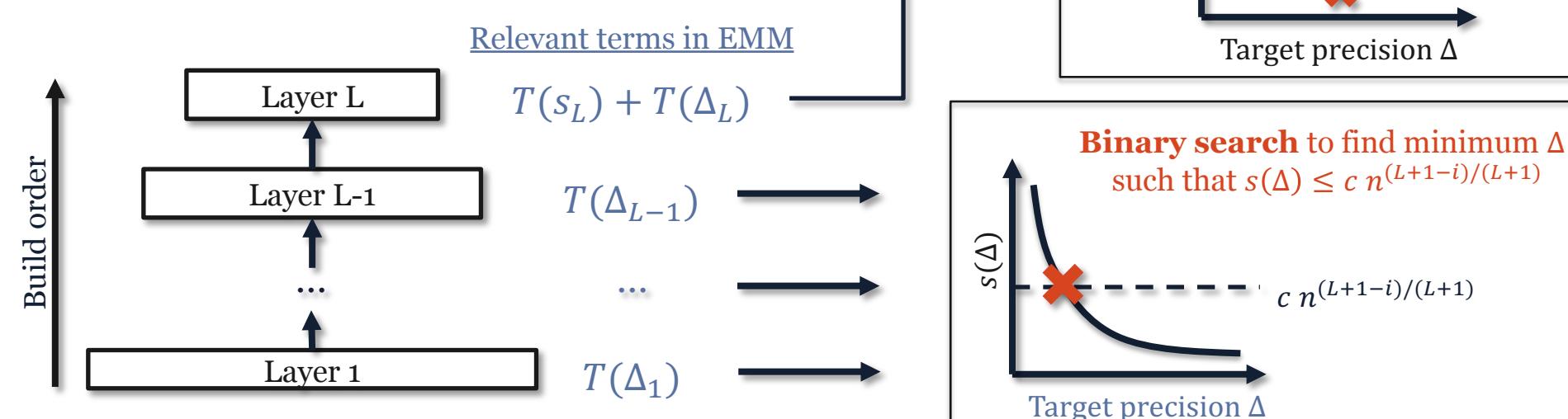


Figure 3: Average latency over first n queries of different systems on wiki dataset. The plot shows $n \in \{1, 2, 4, \dots, 512, 1k, 2k, 4k, \dots, 64k, 70k\}$. Both axes are in the logarithmic scale.

Optimization: Greedy Stack and Balance

Incrementally try number of layers to solve $L^* = \operatorname{argmin}_{L \geq 0} T(s_L) + \sum_{i=1}^L T(\Delta_i)$

For each number of layer L , build from bottom up with bounded size.



Given a precision Δ and a model type, AirIndex greedily partitions the key space and generates a layer of size s .

e.g., greedy packing for step functions, convex hull packing for piecewise linear function

References

- [1] Ryan Marcus, Andreas Kipf, Alexander Renen, Mihai Stoian, Sanchit Misra, Alfons Kemper, Thomas Neumann, and Tim Kraska. 2020. Benchmarking Learned Indexes. Proc. VLDB Endow. 14, 1 (2020), 1–13.
- [2] PostgreSQL. [n. d.]. PostgreSQL: The World's Most Advanced Open Source Relational Database. <https://www.postgresql.org>. [Online; accessed November-12-2021.]
- [3] Siyong Dong, Andrew Kryzka, Yanjin Jin, and Michael Stumm. 2021. RocksDB: Evolution of Development Priorities in a Key-Value Store Serving Large-Scale Applications. ACM Trans. Storage 17, 4, Article 26 (Oct. 2021), 32 pages. <https://doi.org/10.1145/3438340>
- [4] Tim Kraska, Alex Beutel, Ed H. Chi, Jeffrey Dean, and Neoklis Polyzotis. 2018. The case for learned index structures. Proceedings of the ACM SIGMOD International Conference on Management of Data. <https://doi.org/10.1145/3183713.3196909>
- [5] Andreas Kipf, Ryan Marcus, Alexander Renen, Mihai Stoian, Alfons Kemper, Tim Kraska, and Thomas Neumann. 2019. SOSD: A Benchmark for Learned Indexes. NeurIPS Workshop on Machine Learning for Systems (2019)